

## Lifting Modules Shop-Floor

## Max. lifting force 1,000 to 6,000 N, stroke from 200 to 600 mm, manual-hydraulic and electro-mechanical version



## Application

Lifting module for workshop and assembly applications in the industry.

### **Principal use**

- Industrial assembly working places
- Height adjustment of assembly working places in workshops
- Service
- Assembly fixtures
- Adjusting systems in supply processes of mid-sized objects
- · Handling systems for product packing and transfer

### **Fixing and installation**

For fixing of modulub modules or other components of the user at the top plate, the lifting module has an interface 140 x 140.

For fixing of modulub modules at the bottom plate, the lifting module has an interface 200 x 200. This plate can also be used to fix the lifting module on a flat level floor. For fixing, 4 screws M10 of property class 10.9 as well as heavy-duty plugs are to be used.

For increased stability, a base plate, which can be mounted to the bottom plate, is available as accessory. Fixing on the floor is made by means of the base plate.

## **Advantages**

- Simple and intuitive operation
- Working in ergonomically opt
- Sturdy industrial design
- Increase of quality in manufaction and assembly processes
- Increase of assembly through and productivity
- High level of safety against st overloads

<ul> <li>Advantages</li> <li>Simple and intuitive operation</li> <li>Working in ergonomically optimum height</li> <li>Sturdy industrial design</li> <li>Increase of quality in manufacturing and assembly processes</li> <li>Increase of assembly throughput and productivity</li> <li>High level of safety against static overloads</li> </ul>		moduhubLifting modulePart no. 8915-0X-X0-X	
		Technical dataMax. lifting force:1,000 to 6,000 NMax. bending moment:500 NmStroke:200 to 600 mm	
		Operation         • Foot pedal       • Foot switch       • Hand panel         Image: Second secon	
Description		Combinable with the modules	
The lifting module Shop-Floor is particularly suitable for lifting and lowering assembly fix- tures, working tables and demonstration objects in industrial applications as well as for medical treatment equipments in medical applications. In general, lifting modules are used as a base unit of devices for controlled lifting and lowering of loads or for height adjustment only.		<ul> <li>Rotating modules – horizontal axis DMH 200 as per data sheet M 1.101 DMHe 200 as per data sheet M 1.201</li> <li>Tilting modules KMB 100 as per data sheet M 2.101 KME 100 as per data sheet M 2.201</li> <li>Rotating modules – vertical axis DMV 600 as per data sheet M 1.301 DMVe 600 as per data sheet M 1.201</li> <li>Cart modules WMS as per data sheet M 5.101</li> </ul>	
Material		Floor modules     as per data sheet M 6.101	
Lifting profile:	Lifting profile: aluminium, naturally anodised		
Top and bottom plate: aluminium, black anodised	<ul> <li>moduhub interfaces</li> <li>Top plate: 140 x 140 - Ø 10.5 mm</li> <li>Bottom plate: 200 x 200 - Ø 10.5 mm</li> <li>Accessories</li> <li>Electronic control modules for 1, 2, 3 or 4 lifting modules as per data sheet M 8.200</li> <li>Control modules with battery holder as per data sheet M 8.201</li> </ul>		
		<ul> <li>as per data sheet M 8.201</li> <li>Electrical operating elements, lines and connectors</li> </ul>	

- lines and connectors as per data sheet M 8.203
- Base and adaptor plates as per data sheet M 8.100 and M 8.110
- Table plates as per data sheet M 8.130 and M 8.131

Subject to modifications

## Material

# Manual-hydraulic version operation with foot pedal



#### Description

The stroke movement is obtained by a hydraulic lifting drive with single-lever actuation, with oil being pumped by means of a piston pump into a plunger cylinder.

During retraction the oil returns due to the weight of the load from the cylinder back to the reservoir. A defined speed reduction is effected, independent of the load.

The manual-hydraulic variant is particularly sturdy and durable. This variant meets high safety demands and withstands jerking and knocking loads in applications.

According to the application 3 different force levels can be selected. The number of pump strokes depends on the force level.

## Operation

Stroke

Ľ

2

0140 170

225

□150

0

To lift the load, the foot pedal has to be depressed by approx. 40° several times. The pedal returns to its off-position by means of a return spring.

To lower the load, the foot pedal has to be moved upwards by approx. 10°.

<b>Stroke</b> [mm]	<b>A</b> [mm]	<b>A + stroke</b> [mm]	Weight [kg]	
200	420	620	15	
300	520	820	20	
400	620	1,020	25	
500	720	1,220	30	
600	820	1,420	35	
500	720	1,220	30	

Lifting force [N]	Pump strokes per 100 mm	Descent speed [mm/s]
2,000	5	approx. 45
4,000	7	approx. 22
6,000	9	approx. 22

### Accessories

0

Dimensions

ю́ 10 5

₽Ò ₽Ò Detail "X"

• Base plate for increased stability as per data sheet M 8.100

296

#### Important notes

To descend the lifting module a minimum load of approx. 200 N is required.

The lifting module must only be pressure loaded. The centre of gravity should be within the traverse of the fixing screws. If the centre of gravity is outside, the dowelled joint with the floor has to be dimensioned correspondingly. In such cases it is recommended to use a larger base plate.

In case of eccentric load of more than 250 mm, the column cannot descend automatically because of too high friction forces.

The lifting module is designed for applications within closed rooms.

The hydro-manual lifting drive can not be operated with synchronization control.

## Code for part numbers

Part no.

8915-0<mark>X-X</mark>0-H

#### Maximum lifting force -

2 = 2,000 N

4 = 4,000 N

6 = 6.000 N

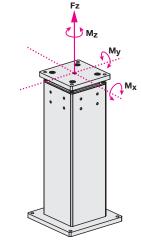
#### Stroke -

- **2** = 200 mm
- **3** = 300 mm
- **4** = 400 mm

**5** = 500 mm **6** = 600 mm

## Maximum lifting force and maximum admissible torque load

## admissible torque load



#### Maximum lifting force Fz

Optionally 2,000 N, 4,000 N or 6,000 N (1,000 N only for the electro-mechanical version)

### Maximum torque load:

Total M <sub>X</sub> /y:	500 Nm
Mz:	300 Nm

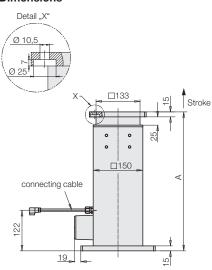
In the case of eccentric loads, it is recommended to compensate these by counterweights. In off-position, the indicated maximum torques may occur.

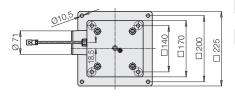
The forces and torques have to be considered by the operator. **During the lifting motion, only 50 % of the maximum values are admitted.** 

## **Electro-mechanical version**



Dimensions





#### Accessories

 Base plate for increased stability as per data sheet M 8.100

#### Description

The lifting motion is generated by an electric motor with a spindle lifting gear.

The electrically operated variant is particularly suitable for positioning and adjusting tasks of working tables as well as for material supply and transport.

They excel by a smooth running.

#### Operation

Lifting and lowering with hand panels or foot switches as per data sheet M 8.203 is triggered by touch control. After release of the pushbutton, the motion will be immediately stopped. The hand panel with memory function allows to store 5 positions, which can be approached via corresponding via corresponding position push-buttons.

(for detailed description see data sheet M 8.203)

#### Synchronization

Up to 4 lifting modules can be operated with synchronization control by a corresponding control module.

For example complete lifting platforms can be designed.

Due to the control modules, variants with 4 or 6 kN lifting force are only suitable for synchronization control with the code letter G.

#### Variants with 2 kN lifting force can be operated in synchronization control in variants G as well as B and I.

Please also pay attention to the instructions for the operation of lifting modules in synchronism on data sheet M 4.005.

Control units with synchronization control for 2, 3, or 4 lifting modules are available.

#### **Technical data**

Electric connection	Plug
Duty cycle	15 % ED
Code class	IP 54
Control voltage	24 V DC

#### Variant E, I and B

Lifting	Lifting speed	Current	
force	(load-dependent)	consumption (load dependent)	
[N]	[mm/s]	[A]	
1,000	3228	7	
2,000	1816	5	
4,000	108	6	
6,000	75	7.5	

#### Variant G

Lifting force	Lifting speed (load-dependent)	Current consumption (load dependent)
[N]	[mm/s]	[A]
2,000	1816	5
4,000	86	4.5
6,000	64	5.5

#### Important notes

Maximum admissible torque load as per manual-hydraulic version (see page 2) . The maximum pull force of the electro-mechanical version is 80% of the push force!

#### Code for part numbers

8915-0<mark>X-X</mark>0-X

#### Maximum lifting force-

- 1 = 1,000 N (only for variant E + B)
- **2** = 2,000 N

Part no.

- **4** = 4,000 N
- **6** = 6,000 N

### Stroke

- **2** = 200 mm
- **3** = 300 mm **4** = 400 mm
- 5 = 500 mm
- **6** = 600 mm
- - - -

#### Electronics

- E = integrated stroke end disconnection (not suitable for synchronization control) with smooth connecting cable, 2.5 m
- G = with incremental stroke measuring system (suitable for synchronization control) with smooth connecting cable, 2.5 m
- I = with incremental stroke measuring system (suitable for memory function) with smooth connecting cable, 2.5 m
- B = with incremental stroke measuring system (suitable for memory function and battery mode)
  - with smooth connecting cable, 1.0 m

In case of the variant with a lifting force of 2,000 N, the electronic variant  ${\bf G}$  is identical with the variant  ${\bf I}.$ 

Delivered will be always variant **G**, which is suitable for memory function as well as for synchronization.

#### Delivery

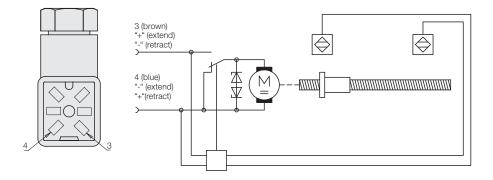
The lifting modules are delivered ready for connection. The connecting cable from the lifting module to the control module is included in the delivery. Operating elements as well as control modules and mains cables can be ordered separately as an accessory.

## Electrical accessories required for a functional system:

- Control module as per data sheet M 8.200
   or
- Control module with battery holder as per data sheet M 8.201
- Hand panels, foot switch and mains cable as per data sheet M 8.203

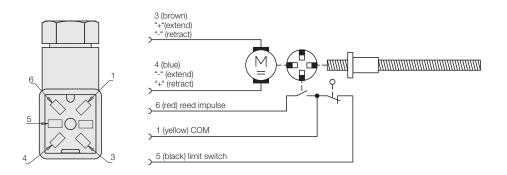
## Circuit diagram and connection

plug-type connectors for lifting modules with stroke end disconnection (with last digit E)

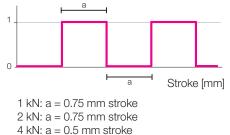


## Circuit diagram and connection

plug-type connectors for lifting modules with incremental stroke measuring system (with last digit I, B and G)



## Resolution of the incremental stroke measuring system



4 kN: a = 0.5 mm stroke6 kN: a = 0.375 mm stroke

•

•